

Higher spin from a world line perspective

Emanuele Latini
Bologna University and LNF, INFN

Pisa, 20 March 2007

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

- Higher Spin and $SO(N)$ Spinning particle
- Gauge fixing
- Gauge fixed partition function
 - ◆ Even N
 - ◆ Odd N
- Pashnev and Sorokin model
- Conclusions and outlook

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

- Higher Spin and $SO(N)$ Spinning particle
- Gauge fixing
- Gauge fixed partition function
 - ◆ Even N
 - ◆ Odd N
- Pashnev and Sorokin model
- Conclusions and outlook

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

- Higher Spin and $SO(N)$ Spinning particle
- Gauge fixing
- Gauge fixed partition function
 - ◆ Even N
 - ◆ Odd N
- Pashnev and Sorokin model
- Conclusions and outlook

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

- Higher Spin and $SO(N)$ Spinning particle
- Gauge fixing
- Gauge fixed partition function
 - ◆ Even N
 - ◆ Odd N
- Pashnev and Sorokin model
- Conclusions and outlook

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

- Higher Spin and $SO(N)$ Spinning particle
- Gauge fixing
- Gauge fixed partition function
 - ◆ Even N
 - ◆ Odd N
- Pashnev and Sorokin model
- Conclusions and outlook

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

- Higher Spin and $SO(N)$ Spinning particle
- Gauge fixing
- Gauge fixed partition function
 - ◆ Even N
 - ◆ Odd N
- Pashnev and Sorokin model
- Conclusions and outlook

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

- Higher Spin and $SO(N)$ Spinning particle
- Gauge fixing
- Gauge fixed partition function
 - ◆ Even N
 - ◆ Odd N
- Pashnev and Sorokin model
- Conclusions and outlook

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

- Higher Spin and $SO(N)$ Spinning particle
- Gauge fixing
- Gauge fixed partition function
 - ◆ Even N
 - ◆ Odd N
- Pashnev and Sorokin model
- Conclusions and outlook

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

$SO(N)$ SPINN. PARTICLE
WITH SUGRA MULTIPLET
ON THE WORLDLINE



SPIN $N/2$ IN $D = 4$,
CONFORMAL PARTICLES
IN " D " DIMENSION

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

$SO(N)$ SPINN. PARTICLE
WITH SUGRA MULTIPLET
ON THE WORLDLINE



SPIN $N/2$ IN $D = 4$,
CONFORMAL PARTICLES
IN " D " DIMENSION

The action for this models reads

$$S[x, \psi_i^\mu, G] = \int_0^1 d\tau \left[\frac{1}{2} \textcolor{red}{e}^{-1} (\dot{x}^\mu - \textcolor{green}{\chi}_i \psi_i^\mu)^2 + \frac{1}{2} \psi_i^\mu (\delta_{ij} \partial_\tau - \textcolor{brown}{a}_{ij}) \psi_j^\mu \right]$$

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

$SO(N)$ SPINN. PARTICLE
WITH SUGRA MULTIPLET
ON THE WORLDLINE



SPIN $N/2$ IN $D = 4$,
CONFORMAL PARTICLES
IN " D " DIMENSION

The action for this models reads

$$S[x, \psi_i^\mu, G] = \int_0^1 d\tau \left[\frac{1}{2} \textcolor{red}{e}^{-1} (\dot{x}^\mu - \textcolor{green}{\chi}_i \psi_i^\mu)^2 + \frac{1}{2} \psi_i^\mu (\delta_{ij} \partial_\tau - \textcolor{brown}{a}_{ij}) \psi_j^\mu \right]$$

The N world line supergravity multiplet contains

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

$SO(N)$ SPINN. PARTICLE
WITH SUGRA MULTIPLET
ON THE WORLDLINE



SPIN $N/2$ IN $D = 4$,
CONFORMAL PARTICLES
IN " D " DIMENSION

The action for this models reads

$$S[x, \psi_i^\mu, G] = \int_0^1 d\tau \left[\frac{1}{2} \textcolor{red}{e}^{-1} (\dot{x}^\mu - \textcolor{green}{x}^\mu \psi_i^\mu)^2 + \frac{1}{2} \psi_i^\mu (\delta_{ij} \partial_\tau - \textcolor{brown}{a}_{ij}) \psi_j^\mu \right]$$

The N world line supergravity multiplet contains

- the enbein e which gauges worldline translations

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

$SO(N)$ SPINN. PARTICLE
WITH SUGRA MULTIPLET
ON THE WORLDLINE



SPIN $N/2$ IN $D = 4$,
CONFORMAL PARTICLES
IN " D " DIMENSION

The action for this models reads

$$S[x, \psi_i^\mu, G] = \int_0^1 d\tau \left[\frac{1}{2} \textcolor{red}{e}^{-1} (\dot{x}^\mu - \textcolor{green}{\chi}_i \psi_i^\mu)^2 + \frac{1}{2} \psi_i^\mu (\delta_{ij} \partial_\tau - \textcolor{brown}{a}_{ij}) \psi_j^\mu \right]$$

The N world line supergravity multiplet contains

- the enbein e which gauges worldline translations
- gravitini χ_i which gauges worldline susy

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

$SO(N)$ SPINN. PARTICLE
WITH SUGRA MULTIPLET
ON THE WORLDLINE



SPIN $N/2$ IN $D = 4$,
CONFORMAL PARTICLES
IN " D " DIMENSION

The action for this models reads

$$S[x, \psi_i^\mu, G] = \int_0^1 d\tau \left[\frac{1}{2} \textcolor{red}{e}^{-1} (\dot{x}^\mu - \textcolor{green}{\chi}_i \psi_i^\mu)^2 + \frac{1}{2} \psi_i^\mu (\delta_{ij} \partial_\tau - \textcolor{brown}{a}_{ij}) \psi_j^\mu \right]$$

The N world line supergravity multiplet contains

- the enbein e which gauges worldline translations
- gravitini χ_i which gauges worldline susy
- gauge field a_{ij} which gauges $SO(N)$ symmetry

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

$SO(N)$ SPINN. PARTICLE
WITH SUGRA MULTIPLET
ON THE WORLDLINE



SPIN $N/2$ IN $D = 4$,
CONFORMAL PARTICLES
IN " D " DIMENSION

The action for this models reads

$$S[x, \psi_i^\mu, G] = \int_0^1 d\tau \left[\frac{1}{2} \textcolor{red}{e}^{-1} (\dot{x}^\mu - \textcolor{green}{\chi}_i \psi_i^\mu)^2 + \frac{1}{2} \psi_i^\mu (\delta_{ij} \partial_\tau - \textcolor{brown}{a}_{ij}) \psi_j^\mu \right]$$

The N world line supergravity multiplet contains

- the enbein e which gauges worldline translations
- gravitini χ_i which gauges worldline susy
- gauge field a_{ij} which gauges $SO(N)$ symmetry

OBJECTIVE

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

$SO(N)$ SPINN. PARTICLE
WITH SUGRA MULTIPLET
ON THE WORLDLINE



SPIN $N/2$ IN $D = 4$,
CONFORMAL PARTICLES
IN " D " DIMENSION

The action for this models reads

$$S[x, \psi_i^\mu, G] = \int_0^1 d\tau \left[\frac{1}{2} \textcolor{red}{e}^{-1} (\dot{x}^\mu - \textcolor{green}{\chi}_i \psi_i^\mu)^2 + \frac{1}{2} \psi_i^\mu (\delta_{ij} \partial_\tau - \textcolor{brown}{a}_{ij}) \psi_j^\mu \right]$$

The N world line supergravity multiplet contains

- the enbein e which gauges worldline translations
- gravitini χ_i which gauges worldline susy
- gauge field a_{ij} which gauges $SO(N)$ symmetry

OBJECTIVE: we want to study the partition function on the circle

$$Z \sim \int_{T^1} \frac{\mathcal{D}X \mathcal{D}G}{\text{Vol(Gauge)}} e^{-S[X, G]}$$

gauge symmetry {

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

$$\text{gauge symmetry} \left\{ \begin{array}{l} \delta e = \dot{\xi} + 2\chi_i \epsilon_i \end{array} \right.$$

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

gauge symmetry $\left\{ \begin{array}{lcl} \delta e & = & \dot{\xi} + 2\chi_i \epsilon_i \\ \delta \chi_i & = & \dot{\epsilon}_i - a_{ij} \epsilon_j + \alpha_{ij} \chi_j \end{array} \right.$

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

$$\text{gauge symmetry} \left\{ \begin{array}{lcl} \delta e & = & \dot{\xi} + 2\chi_i \epsilon_i \\ \delta \chi_i & = & \dot{\epsilon}_i - a_{ij} \epsilon_j + \alpha_{ij} \chi_j \\ \delta a_{ij} & = & \dot{\alpha}_{ij} + \alpha_{im} a_{mj} + \alpha_{jm} a_{im} \end{array} \right.$$

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

$$\text{gauge symmetry} \left\{ \begin{array}{lcl} \delta e & = & \dot{\xi} + 2\chi_i \epsilon_i \\ \delta \chi_i & = & \dot{\epsilon}_i - a_{ij} \epsilon_j + \alpha_{ij} \chi_j \\ \delta a_{ij} & = & \dot{\alpha}_{ij} + \alpha_{im} a_{mj} + \alpha_{jm} a_{im} \end{array} \right.$$

We take fermions and gravitino with antiperiodic boundary condition (ABC)



gravitinos can be completely gauged away

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

$$\text{gauge symmetry} \left\{ \begin{array}{lcl} \delta e & = & \dot{\xi} + 2\chi_i \epsilon_i \\ \delta \chi_i & = & \dot{\epsilon}_i - a_{ij} \epsilon_j + \alpha_{ij} \chi_j \\ \delta a_{ij} & = & \dot{\alpha}_{ij} + \alpha_{im} a_{mj} + \alpha_{jm} a_{im} \end{array} \right.$$

We take fermions and gravitino with antiperiodic boundary condition (ABC)



gravitinos can be completely gauged away

Our gauge choice

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

$$\text{gauge symmetry} \left\{ \begin{array}{lcl} \delta e & = & \dot{\xi} + 2\chi_i \epsilon_i \\ \delta \chi_i & = & \dot{\epsilon}_i - a_{ij} \epsilon_j + \alpha_{ij} \chi_j \\ \delta a_{ij} & = & \dot{\alpha}_{ij} + \alpha_{im} a_{mj} + \alpha_{jm} a_{im} \end{array} \right.$$

We take fermions and gravitino with antiperiodic boundary condition (ABC)



gravitinos can be completely gauged away

Our gauge choice

$$e \rightarrow \beta \in [0, \infty)$$

$$\chi_i \rightarrow 0$$

$$a_{ij} \rightarrow \hat{a}_{ij}(\theta_k) \text{ with } \theta_k \in [0, 2\pi]$$

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

$$\text{gauge symmetry} \left\{ \begin{array}{lcl} \delta e & = & \dot{\xi} + 2\chi_i \epsilon_i \\ \delta \chi_i & = & \dot{\epsilon}_i - a_{ij} \epsilon_j + \alpha_{ij} \chi_j \\ \delta a_{ij} & = & \dot{\alpha}_{ij} + \alpha_{im} a_{mj} + \alpha_{jm} a_{im} \end{array} \right.$$

We take fermions and gravitino with antiperiodic boundary condition (ABC)



gravitinos can be completely gauged away

Our gauge choice

$$e \rightarrow \beta \in [0, \infty)$$

$$\chi_i \rightarrow 0$$

$$a_{ij} \rightarrow \hat{a}_{ij}(\theta_k) \text{ with } \theta_k \in [0, 2\pi]$$

fixes the supergravity multiplet up to some moduli

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

$$\text{gauge symmetry} \left\{ \begin{array}{lcl} \delta e & = & \dot{\xi} + 2\chi_i \epsilon_i \\ \delta \chi_i & = & \dot{\epsilon}_i - a_{ij} \epsilon_j + \alpha_{ij} \chi_j \\ \delta a_{ij} & = & \dot{\alpha}_{ij} + \alpha_{im} a_{mj} + \alpha_{jm} a_{im} \end{array} \right.$$

We take fermions and gravitino with antiperiodic boundary condition (ABC)



gravitinos can be completely gauged away

Our gauge choice

$$e \rightarrow \beta \in [0, \infty)$$

$$\chi_i \rightarrow 0$$

$$a_{ij} \rightarrow \hat{a}_{ij}(\theta_k) \text{ with } \theta_k \in [0, 2\pi]$$

fixes the supergravity multiplet up to some moduli

- β is the usual proper time

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

$$\text{gauge symmetry} \left\{ \begin{array}{lcl} \delta e & = & \dot{\xi} + 2\chi_i \epsilon_i \\ \delta \chi_i & = & \dot{\epsilon}_i - a_{ij} \epsilon_j + \alpha_{ij} \chi_j \\ \delta a_{ij} & = & \dot{\alpha}_{ij} + \alpha_{im} a_{mj} + \alpha_{jm} a_{im} \end{array} \right.$$

We take fermions and gravitino with antiperiodic boundary condition (ABC)



gravitinos can be completely gauged away

Our gauge choice

$$e \rightarrow \beta \in [0, \infty)$$

$$\chi_i \rightarrow 0$$

$$a_{ij} \rightarrow \hat{a}_{ij}(\theta_k) \text{ with } \theta_k \in [0, 2\pi]$$

fixes the supergravity multiplet up to some moduli

- β is the usual proper time
- $\hat{a}_{ij}(\theta_k)$ is some block diagonal matrix we discuss later

Gauge fixed partition function

Summary
 $SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

The gauge fixed partition function reads

$$Z = -\frac{1}{2} \int_0^\infty \frac{d\beta}{\beta} \int \frac{d^D x}{(2\pi\beta)^{\frac{D}{2}}} K_N \prod_{k=1}^r \int_0^{2\pi} \frac{d\theta_k}{2\pi} \text{Det} (\partial_\tau - \hat{a}_{vec})_{ABC}^{\frac{D}{2}-1} \text{Det}' (\partial_\tau - \hat{a}_{adj})_{PBC}$$

Gauge fixed partition function

Summary
 $SO(N)$ spinning
particle model
Gauge fixing
Gauge fixed partition
function

Even N
Odd N
 $Dof(D, N)$
Pashnev and Sorokin
model
 $Dof(D, PS)$
Conclusion
Outlook
The end

The gauge fixed partition function reads

$$Z = -\frac{1}{2} \int_0^\infty \frac{d\beta}{\beta} \int \frac{d^D x}{(2\pi\beta)^{\frac{D}{2}}} K_N \prod_{k=1}^r \int_0^{2\pi} \frac{d\theta_k}{2\pi} \text{Det}_{ABC} (\partial_\tau - \hat{a}_{vec})^{\frac{D}{2}-1} \text{Det}'_{PBC} (\partial_\tau - \hat{a}_{adj})_{PBC}$$

↳ this is a normalization factor we will discuss later

Gauge fixed partition function

Summary
 $SO(N)$ spinning
particle model
Gauge fixing
Gauge fixed partition
function

Even N
Odd N
 $Dof(D, N)$
Pashnev and Sorokin
model
 $Dof(D, PS)$
Conclusion
Outlook
The end

The gauge fixed partition function reads

$$Z = -\frac{1}{2} \int_0^\infty \frac{d\beta}{\beta} \int \frac{d^D x}{(2\pi\beta)^{\frac{D}{2}}} K_N \prod_{k=1}^r \int_0^{2\pi} \frac{d\theta_k}{2\pi} \text{Det}_{ABC} (\partial_\tau - \hat{a}_{vec})^{\frac{D}{2}-1} \text{Det}'_{PBC} (\partial_\tau - \hat{a}_{adj})$$

↳ determinants of the susy ghosts and Majorana fermions which all have antiperiodic boundary conditions (ABC) and transform in the vector representation of $SO(N)$

Gauge fixed partition function

Summary
 $SO(N)$ spinning
particle model
Gauge fixing
Gauge fixed partition
function

Even N
Odd N
 $Dof(D, N)$
Pashnev and Sorokin
model
 $Dof(D, PS)$
Conclusion
Outlook
The end

The gauge fixed partition function reads

$$Z = -\frac{1}{2} \int_0^\infty \frac{d\beta}{\beta} \int \frac{d^D x}{(2\pi\beta)^{\frac{D}{2}}} K_N \prod_{k=1}^r \int_0^{2\pi} \frac{d\theta_k}{2\pi} \text{Det}_{ABC} (\partial_\tau - \hat{a}_{vec})^{\frac{D}{2}-1} \text{Det}'_{PBC} (\partial_\tau - \hat{a}_{adj})$$

- ◊ This determinant is due to the ghosts for the $SO(N)$ gauge symmetry; they transform in the adjoint representation and have periodic boundary conditions (PBC). It's indicated by Det' because it contains zero modes we have to exclude from the determinant

Gauge fixed partition function

Summary
 $SO(N)$ spinning
particle model
Gauge fixing
Gauge fixed partition
function

Even N
Odd N
 $Dof(D, N)$
Pashnev and Sorokin
model
 $Dof(D, PS)$
Conclusion
Outlook
The end

The gauge fixed partition function reads

$$Z = -\frac{1}{2} \int_0^\infty \frac{d\beta}{\beta} \int \frac{d^D x}{(2\pi\beta)^{\frac{D}{2}}}$$

$$K_N \prod_{k=1}^r \int_0^{2\pi} \frac{d\theta_k}{2\pi} \text{Det}_{ABC} (\partial_\tau - \hat{a}_{vec})^{\frac{D}{2}-1} \text{Det}'_{PBC} (\partial_\tau - \hat{a}_{adj})$$



THIS LINE COMPUTES THE NUMBER OF DEGREES OF FREEDOM (Dof) NORMALIZED TO ONE FOR A REAL SCALAR FIELD

Using constant gauge transformations $\Rightarrow a_{ij}$ is block diagonal

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

Using constant gauge transformations $\Rightarrow a_{ij}$ is block diagonal

$$\hat{a}_{ij} = \begin{pmatrix} 0 & \theta_1 & . & 0 & 0 \\ -\theta_1 & 0 & . & 0 & 0 \\ . & . & . & . & . \\ 0 & 0 & . & 0 & \theta_r \\ 0 & 0 & . & -\theta_r & 0 \end{pmatrix} \quad r = \frac{N}{2} = SO(N) \text{ rank}$$

Summary
 $SO(N)$ spinning
particle model

Gauge fixing
Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

Summary
 $SO(N)$ spinning
particle model

Gauge fixing
Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

Using constant gauge transformations $\Rightarrow a_{ij}$ is block diagonal

$$\hat{a}_{ij} = \begin{pmatrix} 0 & \theta_1 & . & 0 & 0 \\ -\theta_1 & 0 & . & 0 & 0 \\ . & . & . & . & . \\ 0 & 0 & . & 0 & \theta_r \\ 0 & 0 & . & -\theta_r & 0 \end{pmatrix} \quad r = \frac{N}{2} = SO(N) \text{ rank}$$

Using large gauge transformation $\Rightarrow \theta_r \sim \theta_r + 2\pi n \quad \theta_k = \text{angles}$

Summary
 $SO(N)$ spinning
particle model

Gauge fixing
Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

Using constant gauge transformations $\Rightarrow a_{ij}$ is block diagonal

$$\hat{a}_{ij} = \begin{pmatrix} 0 & \theta_1 & . & 0 & 0 \\ -\theta_1 & 0 & . & 0 & 0 \\ . & . & . & . & . \\ 0 & 0 & . & 0 & \theta_r \\ 0 & 0 & . & -\theta_r & 0 \end{pmatrix} \quad r = \frac{N}{2} = SO(N) \text{ rank}$$

Using large gauge transformation $\Rightarrow \theta_r \sim \theta_r + 2\pi n \quad \theta_k = \text{angles}$

◆ $\text{Det}'(\partial_\tau - \hat{a}_{adj})_{PBC} = \prod_{k < l} (2 \sin \frac{\theta_k + \theta_l}{2})^2 (2 \sin \frac{\theta_k - \theta_l}{2})^2$

Summary
 $SO(N)$ spinning
 particle model
 Gauge fixing
 Gauge fixed partition
 function
Even N
 Odd N
 $Dof(D, N)$
 Pashnev and Sorokin
 model
 $Dof(D, PS)$
 Conclusion
 Outlook
 The end

Using constant gauge transformations $\Rightarrow a_{ij}$ is block diagonal

$$\hat{a}_{ij} = \begin{pmatrix} 0 & \theta_1 & . & 0 & 0 \\ -\theta_1 & 0 & . & 0 & 0 \\ . & . & . & . & . \\ 0 & 0 & . & 0 & \theta_r \\ 0 & 0 & . & -\theta_r & 0 \end{pmatrix} \quad r = \frac{N}{2} = SO(N) \text{ rank}$$

Using large gauge transformation $\Rightarrow \theta_r \sim \theta_r + 2\pi n \quad \theta_k = \text{angles}$

◇ $\text{Det}' (\partial_\tau - \hat{a}_{adj})_{PBC} = \prod_{k < l} (2 \sin \frac{\theta_k + \theta_l}{2})^2 (2 \sin \frac{\theta_k - \theta_l}{2})^2$

◆ $\text{Det} (\partial_\tau - \hat{a}_{vec})_{ABC}^{\frac{D}{2}-1} = \prod_{k=1}^r (2 \cos \frac{\theta_k}{2})^{D-2}$

Summary
 $SO(N)$ spinning
 particle model
 Gauge fixing
 Gauge fixed partition
 function
Even N
 Odd N
 $Dof(D, N)$
 Pashnev and Sorokin
 model
 $Dof(D, PS)$
 Conclusion
 Outlook
 The end

Using constant gauge transformations $\Rightarrow a_{ij}$ is block diagonal

$$\hat{a}_{ij} = \begin{pmatrix} 0 & \theta_1 & . & 0 & 0 \\ -\theta_1 & 0 & . & 0 & 0 \\ . & . & . & . & . \\ 0 & 0 & . & 0 & \theta_r \\ 0 & 0 & . & -\theta_r & 0 \end{pmatrix} \quad r = \frac{N}{2} = SO(N) \text{ rank}$$

Using large gauge transformation $\Rightarrow \theta_r \sim \theta_r + 2\pi n \quad \theta_k = \text{angles}$

◇ $\text{Det}' (\partial_\tau - \hat{a}_{adj})_{PBC} = \prod_{k < l} (2 \sin \frac{\theta_k + \theta_l}{2})^2 (2 \sin \frac{\theta_k - \theta_l}{2})^2$

◆ $\text{Det} (\partial_\tau - \hat{a}_{vec})_{ABC}^{\frac{D}{2}-1} = \prod_{k=1}^r (2 \cos \frac{\theta_k}{2})^{D-2}$

¤ $K_N = \frac{2}{2^r} \frac{1}{r!}$

Summary
 $SO(N)$ spinning
 particle model
 Gauge fixing
 Gauge fixed partition
 function
Even N
Odd N
 $Dof(D, N)$
 Pashnev and Sorokin
 model
 $Dof(D, PS)$
 Conclusion
 Outlook
 The end

Using constant gauge transformations $\Rightarrow a_{ij}$ is block diagonal

$$\hat{a}_{ij} = \begin{pmatrix} 0 & \theta_1 & . & 0 & 0 \\ -\theta_1 & 0 & . & 0 & 0 \\ . & . & . & . & . \\ 0 & 0 & . & 0 & \theta_r \\ 0 & 0 & . & -\theta_r & 0 \end{pmatrix} \quad r = \frac{N}{2} = SO(N) \text{ rank}$$

Using large gauge transformation $\Rightarrow \theta_r \sim \theta_r + 2\pi n \quad \theta_k = \text{angles}$

◇ $\text{Det}' (\partial_\tau - \hat{a}_{adj})_{PBC} = \prod_{k < l} (2 \sin \frac{\theta_k + \theta_l}{2})^2 (2 \sin \frac{\theta_k - \theta_l}{2})^2$

⬤ $\text{Det} (\partial_\tau - \hat{a}_{vec})_{ABC}^{\frac{D}{2}-1} = \prod_{k=1}^r (2 \cos \frac{\theta_k}{2})^{D-2}$

¤ $K_N = \frac{2}{2^r} \frac{1}{r!}$

Using constant $SO(n)$ transformation one can only change signs to pairs of angles simultaneously

$$\begin{pmatrix} +\Theta_i & . & 0 \\ . & . & . \\ 0 & . & +\Theta_j \end{pmatrix}$$

Summary
 $SO(N)$ spinning
 particle model
 Gauge fixing
 Gauge fixed partition
 function
Even N
Odd N
 $Dof(D, N)$
 Pashnev and Sorokin
 model
 $Dof(D, PS)$
 Conclusion
 Outlook
 The end

Using constant gauge transformations $\Rightarrow a_{ij}$ is block diagonal

$$\hat{a}_{ij} = \begin{pmatrix} 0 & \theta_1 & . & 0 & 0 \\ -\theta_1 & 0 & . & 0 & 0 \\ . & . & . & . & . \\ 0 & 0 & . & 0 & \theta_r \\ 0 & 0 & . & -\theta_r & 0 \end{pmatrix} \quad r = \frac{N}{2} = SO(N) \text{ rank}$$

Using large gauge transformation $\Rightarrow \theta_r \sim \theta_r + 2\pi n \quad \theta_k = \text{angles}$

◊ $\text{Det}' (\partial_\tau - \hat{a}_{adj})_{PBC} = \prod_{k < l} (2 \sin \frac{\theta_k + \theta_l}{2})^2 (2 \sin \frac{\theta_k - \theta_l}{2})^2$

⌚ $\text{Det} (\partial_\tau - \hat{a}_{vec})_{ABC}^{\frac{D}{2}-1} = \prod_{k=1}^r (2 \cos \frac{\theta_k}{2})^{D-2}$

⌚ $K_N = \frac{2}{2^r} \frac{1}{r!}$

Using constant $SO(n)$ transformation one can only change signs to pairs of angles simultaneously

$$\begin{pmatrix} -\Theta_i & . & 0 \\ . & . & . \\ 0 & . & -\Theta_j \end{pmatrix}$$

Summary
 $SO(N)$ spinning
 particle model
 Gauge fixing
 Gauge fixed partition
 function
Even N
Odd N
 $Dof(D, N)$
 Pashnev and Sorokin
 model
 $Dof(D, PS)$
 Conclusion
 Outlook
 The end

Using constant gauge transformations $\Rightarrow a_{ij}$ is block diagonal

$$\hat{a}_{ij} = \begin{pmatrix} 0 & \theta_1 & . & 0 & 0 \\ -\theta_1 & 0 & . & 0 & 0 \\ . & . & . & . & . \\ 0 & 0 & . & 0 & \theta_r \\ 0 & 0 & . & -\theta_r & 0 \end{pmatrix} \quad r = \frac{N}{2} = SO(N) \text{ rank}$$

Using large gauge transformation $\Rightarrow \theta_r \sim \theta_r + 2\pi n \quad \theta_k = \text{angles}$

◇ $\text{Det}' (\partial_\tau - \hat{a}_{adj})_{PBC} = \prod_{k < l} (2 \sin \frac{\theta_k + \theta_l}{2})^2 (2 \sin \frac{\theta_k - \theta_l}{2})^2$

⬤ $\text{Det} (\partial_\tau - \hat{a}_{vec})_{ABC}^{\frac{D}{2}-1} = \prod_{k=1}^r (2 \cos \frac{\theta_k}{2})^{D-2}$

¤ $K_N = \frac{2}{2^r} \frac{1}{r!}$

this factor is due to the fact that with a $SO(N)$ transformation one can permute the angles θ_i

Summary

 $SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
functionEven N Odd N $Dof(D, N)$ Pashnev and Sorokin
model $Dof(D, PS)$

Conclusion

Outlook

The end

$$Dof(D, N = 2r) = \frac{2}{2^r r!} \prod_{k=1}^r \int_0^{2\pi} \frac{d\theta_k}{2\pi} (2\cos\frac{\theta}{2})^{D-2} \\ \prod_{k < l} [(2\cos\frac{\theta_k}{2})^2 - (2\cos\frac{\theta_l}{2})^2]$$

◆ $\text{Det}' (\partial_\tau - \hat{a}_{adj})_{PBC} = \prod_{k < l} (2 \sin \frac{\theta_k + \theta_l}{2})^2 (2 \sin \frac{\theta_k - \theta_l}{2})^2$

⬤ $\text{Det} (\partial_\tau - \hat{a}_{vec})_{ABC}^{\frac{D}{2}-1} = \prod_{k=1}^r (2 \cos \frac{\theta_k}{2})^{D-2}$

¤ $K_N = \frac{2}{2^r} \frac{1}{r!}$

in a way somewhat similar to the even case one finds:

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

in a way somewhat similar to the even case one finds:

$$\hat{a}_{ij} = \begin{pmatrix} 0 & \theta_1 & . & 0 & 0 & 0 \\ -\theta_1 & 0 & . & 0 & 0 & 0 \\ . & . & . & . & . & . \\ 0 & 0 & 0 & 0 & \theta_r & 0 \\ 0 & 0 & 0 & -\theta_r & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} \quad r = \frac{N-1}{2} = SO(N) \text{ rank}$$

Summary
 $SO(N)$ spinning
particle model

Gauge fixing
Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

in a way somewhat similar to the even case one finds:

$$\hat{a}_{ij} = \begin{pmatrix} 0 & \theta_1 & . & 0 & 0 & 0 \\ -\theta_1 & 0 & . & 0 & 0 & 0 \\ . & . & . & . & . & . \\ 0 & 0 & 0 & 0 & \theta_r & 0 \\ 0 & 0 & 0 & -\theta_r & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} \quad r = \frac{N-1}{2} = SO(N) \text{ rank}$$

◆ $\text{Det}' (\partial_\tau - \hat{a}_{adj})_{PBC} = 64 \prod_{k=1}^r \sin^2 \frac{\theta_k}{2} \prod_{k < l} \sin^2 \frac{\theta_k + \theta_l}{2} \sin^2 \frac{\theta_k - \theta_l}{2}$

Summary
 $SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

in a way somewhat similar to the even case one finds:

$$\hat{a}_{ij} = \begin{pmatrix} 0 & \theta_1 & . & 0 & 0 & 0 \\ -\theta_1 & 0 & . & 0 & 0 & 0 \\ . & . & . & . & . & . \\ 0 & 0 & 0 & 0 & \theta_r & 0 \\ 0 & 0 & 0 & -\theta_r & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} \quad r = \frac{N-1}{2} = SO(N) \text{ rank}$$

- ◊ $\text{Det}' (\partial_\tau - \hat{a}_{adj})_{PBC} = 64 \prod_{k=1}^r \sin^2 \frac{\theta_k}{2} \prod_{k < l} \sin^2 \frac{\theta_k + \theta_l}{2} \sin^2 \frac{\theta_k - \theta_l}{2}$
- ⬤ $\text{Det} (\partial_\tau - \hat{a}_{vec})_{ABC}^{\frac{D}{2}-1} = 2^{\frac{D}{2}-1} \prod_{k=1}^r (2 \cos \frac{\theta_k}{2})^{D-2}$

in a way somewhat similar to the even case one finds:

$$\hat{a}_{ij} = \begin{pmatrix} 0 & \theta_1 & . & 0 & 0 & 0 \\ -\theta_1 & 0 & . & 0 & 0 & 0 \\ . & . & . & . & . & . \\ 0 & 0 & 0 & 0 & \theta_r & 0 \\ 0 & 0 & 0 & -\theta_r & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} \quad r = \frac{N-1}{2} = SO(N) \text{ rank}$$

◊ $\text{Det}' (\partial_\tau - \hat{a}_{adj})_{PBC} = 64 \prod_{k=1}^r \sin^2 \frac{\theta_k}{2} \prod_{k < l} \sin^2 \frac{\theta_k + \theta_l}{2} \sin^2 \frac{\theta_k - \theta_l}{2}$

⌚ $\text{Det} (\partial_\tau - \hat{a}_{vec})_{ABC}^{\frac{D}{2}-1} = 2^{\frac{D}{2}-1} \prod_{k=1}^r (2 \cos \frac{\theta_k}{2})^{D-2}$

⌚ $K_N = \frac{1}{2^r} \frac{1}{r!}$

Summary
 $SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

Summary
 $SO(N)$ spinning
 particle model
 Gauge fixing
 Gauge fixed partition
 function
 Even N
Odd N
 $Dof(D, N)$
 Pashnev and Sorokin
 model
 $Dof(D, PS)$
 Conclusion
 Outlook
 The end

in a way somewhat similar to the even case one finds:

$$\hat{a}_{ij} = \begin{pmatrix} 0 & \theta_1 & . & 0 & 0 & 0 \\ -\theta_1 & 0 & . & 0 & 0 & 0 \\ . & . & . & . & . & . \\ 0 & 0 & 0 & 0 & \theta_r & 0 \\ 0 & 0 & 0 & -\theta_r & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} \quad r = \frac{N-1}{2} = SO(N) \text{ rank}$$

- ◊ $\text{Det}' (\partial_\tau - \hat{a}_{adj})_{PBC} = 64 \prod_{k=1}^r \sin^2 \frac{\theta_k}{2} \prod_{k < l} \sin^2 \frac{\theta_k + \theta_l}{2} \sin^2 \frac{\theta_k - \theta_l}{2}$
- ⌚ $\text{Det} (\partial_\tau - \hat{a}_{vec})_{ABC}^{\frac{D}{2}-1} = 2^{\frac{D}{2}-1} \prod_{k=1}^r (2 \cos \frac{\theta_k}{2})^{D-2}$

$$\natural \quad K_N = \frac{1}{2^r} \frac{1}{r!}$$

the factor 2 that appeared in the even case is not included here since one can always reflect the last coordinate to obtain an $SO(N)$ transformation that changes θ_k into $-\theta_k$

$$\begin{pmatrix} +\Theta_i & . & 0 \\ . & . & . \\ 0 & . & +\Theta_j \end{pmatrix}$$

Summary
 $SO(N)$ spinning
 particle model
 Gauge fixing
 Gauge fixed partition
 function
 Even N
Odd N
 $Dof(D, N)$
 Pashnev and Sorokin
 model
 $Dof(D, PS)$
 Conclusion
 Outlook
 The end

in a way somewhat similar to the even case one finds:

$$\hat{a}_{ij} = \begin{pmatrix} 0 & \theta_1 & . & 0 & 0 & 0 \\ -\theta_1 & 0 & . & 0 & 0 & 0 \\ . & . & . & . & . & . \\ 0 & 0 & 0 & 0 & \theta_r & 0 \\ 0 & 0 & 0 & -\theta_r & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} \quad r = \frac{N-1}{2} = SO(N) \text{ rank}$$

- ◊ $\text{Det}' (\partial_\tau - \hat{a}_{adj})_{PBC} = 64 \prod_{k=1}^r \sin^2 \frac{\theta_k}{2} \prod_{k < l} \sin^2 \frac{\theta_k + \theta_l}{2} \sin^2 \frac{\theta_k - \theta_l}{2}$
- ⌚ $\text{Det} (\partial_\tau - \hat{a}_{vec})_{ABC}^{\frac{D}{2}-1} = 2^{\frac{D}{2}-1} \prod_{k=1}^r (2 \cos \frac{\theta_k}{2})^{D-2}$

$$\natural \quad K_N = \frac{1}{2^r} \frac{1}{r!}$$

the factor 2 that appeared in the even case is not included here since one can always reflect the last coordinate to obtain an $SO(N)$ transformation that changes θ_k into $-\theta_k$

$$\begin{pmatrix} -\Theta_i & . & 0 \\ . & . & . \\ 0 & . & +\Theta_j \end{pmatrix}$$

Summary
 $SO(N)$ spinning
 particle model
 Gauge fixing
 Gauge fixed partition
 function
 Even N
Odd N
 $Dof(D, N)$
 Pashnev and Sorokin
 model
 $Dof(D, PS)$
 Conclusion
 Outlook
 The end

in a way somewhat similar to the even case one finds:

$$\hat{a}_{ij} = \begin{pmatrix} 0 & \theta_1 & . & 0 & 0 & 0 \\ -\theta_1 & 0 & . & 0 & 0 & 0 \\ . & . & . & . & . & . \\ 0 & 0 & 0 & 0 & \theta_r & 0 \\ 0 & 0 & 0 & -\theta_r & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} \quad r = \frac{N-1}{2} = SO(N) \text{ rank}$$

- ◊ $\text{Det}' (\partial_\tau - \hat{a}_{adj})_{PBC} = 64 \prod_{k=1}^r \sin^2 \frac{\theta_k}{2} \prod_{k < l} \sin^2 \frac{\theta_k + \theta_l}{2} \sin^2 \frac{\theta_k - \theta_l}{2}$
- ⌚ $\text{Det} (\partial_\tau - \hat{a}_{vec})_{ABC}^{\frac{D}{2}-1} = 2^{\frac{D}{2}-1} \prod_{k=1}^r (2 \cos \frac{\theta_k}{2})^{D-2}$

$$\natural \quad K_N = \frac{1}{2^r} \frac{1}{r!}$$

the factor 2 that appeared in the even case is not included here since one can always reflect the last coordinate to obtain an $SO(N)$ transformation that changes θ_k into $-\theta_k$

$$\begin{pmatrix} +\Theta_i & . & 0 \\ . & . & . \\ 0 & . & -\Theta_j \end{pmatrix}$$

Summary
 $SO(N)$ spinning
 particle model
 Gauge fixing
 Gauge fixed partition
 function
 Even N
Odd N
 $Dof(D, N)$
 Pashnev and Sorokin
 model
 $Dof(D, PS)$
 Conclusion
 Outlook
 The end

in a way somewhat similar to the even case one finds:

$$\hat{a}_{ij} = \begin{pmatrix} 0 & \theta_1 & . & 0 & 0 & 0 \\ -\theta_1 & 0 & . & 0 & 0 & 0 \\ . & . & . & . & . & . \\ 0 & 0 & 0 & 0 & \theta_r & 0 \\ 0 & 0 & 0 & -\theta_r & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} \quad r = \frac{N-1}{2} = SO(N) \text{ rank}$$

- ◊ $\text{Det}' (\partial_\tau - \hat{a}_{adj})_{PBC} = 64 \prod_{k=1}^r \sin^2 \frac{\theta_k}{2} \prod_{k < l} \sin^2 \frac{\theta_k + \theta_l}{2} \sin^2 \frac{\theta_k - \theta_l}{2}$
- ⌚ $\text{Det} (\partial_\tau - \hat{a}_{vec})_{ABC}^{\frac{D}{2}-1} = 2^{\frac{D}{2}-1} \prod_{k=1}^r (2 \cos \frac{\theta_k}{2})^{D-2}$

$$\natural \quad K_N = \frac{1}{2^r} \frac{1}{r!}$$

due to the permutation

Summary

 $SO(N)$ spinning
particle modelGauge fixing
Gauge fixed partition
functionEven N Odd N $Dof(D, N)$ Pashnev and Sorokin
model $Dof(D, PS)$

Conclusion

Outlook

The end

$$Dof(D, N = 2r + 1) = \frac{2^{\frac{D}{2}-1}}{2^r r!} \prod_{k=1}^r \int_0^{2\pi} \frac{d\theta_k}{2\pi} (2\cos \frac{\theta_k}{2})^{D-2} (2\sin \frac{\theta_k}{2})^2$$

$$\prod_{k < l} [(2\sin \frac{\theta_k + \theta_l}{2})^2 (2\sin \frac{\theta_k - \theta_l}{2})^2]$$

◆ $\text{Det}' (\partial_\tau - \hat{a}_{adj})_{PBC} = 64 \prod_{k=1}^r \sin^2 \frac{\theta_k}{2} \prod_{k < l} \sin^2 \frac{\theta_k + \theta_l}{2} \sin^2 \frac{\theta_k - \theta_l}{2}$

⬤ $\text{Det} (\partial_\tau - \hat{a}_{vec})_{ABC}^{\frac{D}{2}-1} = 2^{\frac{D}{2}-1} \prod_{k=1}^r (2 \cos \frac{\theta_k}{2})^{D-2}$

⊣ $K_N = \frac{1}{2^r} \frac{1}{r!}$

We have used "orthogonal polynomial method" to compute the integral:

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

Summary
 $SO(N)$ spinning
particle model
Gauge fixing
Gauge fixed partition
function
Even N
Odd N
 $Dof(D, N)$
Pashnev and Sorokin
model
 $Dof(D, PS)$
Conclusion
Outlook
The end

We have used "orthogonal polynomial method" to compute the integral:

$$Dof(2d, 2r) = 2^{r-1} \frac{(2d-2)!}{[(d-1)!]^2} \prod_{k=1}^{r-1} \frac{k (2k-1)! (2k+2d-3)!}{(2k+d-2)! (2k+d-1)!}$$

$$Dof(2d, 2r+1) = \frac{2^{d-2+r} (2d-2)!}{d[(d-1)!]^2} \prod_{k=1}^{r-1} \frac{(k+d-1) (2k+1)! (2k+2d-3)!}{(2k+d-1)! (2k+d)!}$$

Summary
 $SO(N)$ spinning
particle model
Gauge fixing
Gauge fixed partition
function
Even N
Odd N
 $Dof(D, N)$
Pashnev and Sorokin
model
 $Dof(D, PS)$
Conclusion
Outlook
The end

We have used "orthogonal polynomial method" to compute the integral:

$$Dof(2d, 2r) = 2^{r-1} \frac{(2d-2)!}{[(d-1)!]^2} \prod_{k=1}^{r-1} \frac{k (2k-1)! (2k+2d-3)!}{(2k+d-2)! (2k+d-1)!}$$

$$Dof(2d, 2r+1) = \frac{2^{d-2+r} (2d-2)!}{d[(d-1)!]^2} \prod_{k=1}^{r-1} \frac{(k+d-1) (2k+1)! (2k+2d-3)!}{(2k+d-1)! (2k+d)!}$$

OBSERVATION:

Summary
 $SO(N)$ spinning
 particle model
 Gauge fixing
 Gauge fixed partition
 function
 Even N
 Odd N
 Dof(D, N)
 Pashnev and Sorokin
 model
 Dof(D, PS)
 Conclusion
 Outlook
 The end

We have used "orthogonal polynomial method" to compute the integral:

$$Dof(2d, 2r) = 2^{r-1} \frac{(2d-2)!}{[(d-1)!]^2} \prod_{k=1}^{r-1} \frac{k (2k-1)! (2k+2d-3)!}{(2k+d-2)! (2k+d-1)!}$$

$$Dof(2d, 2r+1) = \frac{2^{d-2+r} (2d-2)!}{d[(d-1)!]^2} \prod_{k=1}^{r-1} \frac{(k+d-1) (2k+1)! (2k+2d-3)!}{(2k+d-1)! (2k+d)!}$$

OBSERVATION:

$$Dof(2d+1, N) = 0 \quad \forall N > 1$$

Summary
 $SO(N)$ spinning
particle model
Gauge fixing
Gauge fixed partition
function
Even N
Odd N
 $Dof(D, N)$
Pashnev and Sorokin
model
 $Dof(D, PS)$
Conclusion
Outlook
The end

We have used "orthogonal polynomial method" to compute the integral:

$$Dof(2d, 2r) = 2^{r-1} \frac{(2d-2)!}{[(d-1)!]^2} \prod_{k=1}^{r-1} \frac{k (2k-1)! (2k+2d-3)!}{(2k+d-2)! (2k+d-1)!}$$

$$Dof(2d, 2r+1) = \frac{2^{d-2+r} (2d-2)!}{d[(d-1)!]^2} \prod_{k=1}^{r-1} \frac{(k+d-1) (2k+1)! (2k+2d-3)!}{(2k+d-1)! (2k+d)!}$$

SPECIAL CASES:

Summary
 $SO(N)$ spinning
 particle model
 Gauge fixing
 Gauge fixed partition
 function
 Even N
 Odd N
 Dof(D, N)
 Pashnev and Sorokin
 model
 Dof(D, PS)
 Conclusion
 Outlook
 The end

We have used "orthogonal polynomial method" to compute the integral:

$$Dof(2d, 2r) = 2^{r-1} \frac{(2d-2)!}{[(d-1)!]^2} \prod_{k=1}^{r-1} \frac{k (2k-1)! (2k+2d-3)!}{(2k+d-2)! (2k+d-1)!}$$

$$Dof(2d, 2r+1) = \frac{2^{d-2+r} (2d-2)!}{d[(d-1)!]^2} \prod_{k=1}^{r-1} \frac{(k+d-1) (2k+1)! (2k+2d-3)!}{(2k+d-1)! (2k+d)!}$$

SPECIAL CASES:

$$Dof(2, N) = 1, \quad \forall N$$

$$Dof(4, N) = 2, \quad \forall N$$

$$Dof(2d, 2) = \frac{(2d-2)!}{[(d-1)!]^2}$$

$$Dof(2d, 3) = \frac{2^{d-1}}{d} \frac{(2d-2)!}{[(d-1)!]^2}$$

Pashnev and Sorokin model

For $N = 4$ the gauge group is $SO(4) = SU(2) \times SU(2)$. In the literature, by Pashnev and Sorokin, also the model with a factor $SU(2)$ gauged and the other $SU(2)$ left as a global symmetry has been considered

Summary
 $SO(N)$ spinning
particle model
Gauge fixing
Gauge fixed partition
function
Even N
Odd N
 $Dof(D, N)$
Pashnev and Sorokin
model
 $Dof(D, PS)$
Conclusion
Outlook
The end

Pashnev and Sorokin model

For $N = 4$ the gauge group is $SO(4) = SU(2) \times SU(2)$. In the literature, by Pashnev and Sorokin, also the model with a factor $SU(2)$ gauged and the other $SU(2)$ left as a global symmetry has been considered.

Quantization of this model seems to produce an inconsistency:

- Summary
- $SO(N)$ spinning particle model
- Gauge fixing
- Gauge fixed partition function
- Even N
- Odd N
- $Dof(D, N)$
- Pashnev and Sorokin model
- $Dof(D, PS)$
- Conclusion
- Outlook
- The end

For $N = 4$ the gauge group is $SO(4) = SU(2) \times SU(2)$. In the literature, by Pashnev and Sorokin, also the model with a factor $SU(2)$ gauged and the other $SU(2)$ left as a global symmetry has been considered.

Quantization of this model seems to produce an inconsistency:

Dirac operatorial quantization

seems to describe

- three scalar
- a spin 2

$$Dof(D = 4, PS) = 5$$

Gupta Bleuler quantization

seems to describe

- two scalar
- a spin 2

$$Dof(D = 4, PS) = 4$$

In this case the number of degrees of freedom is given by

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

In this case the number of degrees of freedom is given by

$$Dof(D, PS) = \frac{1}{2} \int_0^{2\pi} \frac{d\theta}{2\pi} (2 \cos \frac{\theta}{2})^{2(D-2)} (2 \sin \theta)^2 =$$

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

In this case the number of degrees of freedom is given by

$$Dof(D, PS) = \frac{1}{2} \int_0^{2\pi} \frac{d\theta}{2\pi} (2 \cos \frac{\theta}{2})^{2(D-2)} (2 \sin \theta)^2 = \frac{2^{D-1} (2D-3)!!}{D!}$$

Summary
 $SO(N)$ spinning
particle model

Gauge fixing
Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

In this case the number of degrees of freedom is given by

$$Dof(D, PS) = \frac{1}{2} \int_0^{2\pi} \frac{d\theta}{2\pi} (2 \cos \frac{\theta}{2})^{2(D-2)} (2 \sin \theta)^2 = \frac{2^{D-1} (2D-3)!!}{D!}$$

D	Dof
2	1
3	2
4	5
5	14
.	.
.	.

Summary
 $SO(N)$ spinning
particle model

Gauge fixing
Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

In this case the number of degrees of freedom is given by

$$Dof(D, PS) = \frac{1}{2} \int_0^{2\pi} \frac{d\theta}{2\pi} (2 \cos \frac{\theta}{2})^{2(D-2)} (2 \sin \theta)^2 = \frac{2^{D-1} (2D-3)!!}{D!}$$

D	Dof
2	1
3	2
4	5
5	14
.	.
.	.

OBSERVATION:

Summary
 $SO(N)$ spinning
particle model
Gauge fixing
Gauge fixed partition
function
Even N
Odd N
 $Dof(D, N)$
Pashnev and Sorokin
model
 $Dof(D, PS)$
Conclusion
Outlook
The end

Summary
 $SO(N)$ spinning
particle model

Gauge fixing
Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

In this case the number of degrees of freedom is given by

$$Dof(D, PS) = \frac{1}{2} \int_0^{2\pi} \frac{d\theta}{2\pi} (2 \cos \frac{\theta}{2})^{2(D-2)} (2 \sin \theta)^2 = \frac{2^{D-1} (2D-3)!!}{D!}$$

D	Dof
2	1
3	2
4	5
5	14
.	.
.	.

OBSERVATION:

- Our analysis gives 5 degrees of freedom in $D = 4$, corresponding presumably to a graviton and three scalars.

Summary
 $SO(N)$ spinning
 particle model

Gauge fixing
 Gauge fixed partition
 function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
 model

$Dof(D, PS)$

Conclusion

Outlook

The end

In this case the number of degrees of freedom is given by

$$Dof(D, PS) = \frac{1}{2} \int_0^{2\pi} \frac{d\theta}{2\pi} (2 \cos \frac{\theta}{2})^{2(D-2)} (2 \sin \theta)^2 = \frac{2^{D-1} (2D-3)!!}{D!}$$

D	Dof
2	1
3	2
4	5
5	14
.	.
.	.

OBSERVATION:

- Our analysis gives 5 degrees of freedom in $D = 4$, corresponding presumably to a graviton and three scalars.
- The latter is non vanishing for *any* space-time dimension D , implying that - in this case - odd-dimensional models are non empty.

- We have studied the one-loop quantization of spinning particles with a gauged $SO(N)$ extended supergravity on the worldline, propagating on flat target space

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end

- We have studied the one-loop quantization of spinning particles with a gauged $SO(N)$ extended supergravity on the worldline, propagating on flat target space
- We have obtained the measure on the moduli space of the $SO(N)$

Summary
 $SO(N)$ spinning particle model
Gauge fixing
Gauge fixed partition function
Even N
Odd N
 $Dof(D, N)$
Pashnev and Sorokin model
 $Dof(D, PS)$
Conclusion
Outlook
The end

- We have studied the one-loop quantization of spinning particles with a gauged $SO(N)$ extended supergravity on the worldline, propagating on flat target space
- We have obtained the measure on the moduli space of the $SO(N)$
- and we have used it to compute the propagating physical degrees of freedom

Summary
 $SO(N)$ spinning particle model
Gauge fixing
Gauge fixed partition function
Even N
Odd N
 $Dof(D, N)$
Pashnev and Sorokin model
 $Dof(D, PS)$
Conclusion
Outlook
The end

- We have studied the one-loop quantization of spinning particles with a gauged $SO(N)$ extended supergravity on the worldline, propagating on flat target space
- We have obtained the measure on the moduli space of the $SO(N)$
- and we have used it to compute the propagating physical degrees of freedom
- We have also studied the $N = 4$ case with an $SU(2)$ symmetry left as a global one and shown that this propagate 5 degrees of freedom in $D = 4$ corresponding probably to 3 scalars and a spin 2 field

Summary
 $SO(N)$ spinning particle model
Gauge fixing
Gauge fixed partition function
Even N
Odd N
 $Dof(D, N)$
Pashnev and Sorokin model
 $Dof(D, PS)$
Conclusion
Outlook
The end

- Would be interesting to study the one-loop partition function of this model coupled to AdS background

Summary
 $SO(N)$ spinning particle model
Gauge fixing
Gauge fixed partition function
Even N
Odd N
 $Dof(D, N)$
Pashnev and Sorokin model
 $Dof(D, PS)$
Conclusion
Outlook
The end

- Would be interesting to study the one-loop partition function of this model coupled to AdS background
- and study from the worldline point of view how one could introduce more general couplings.

Summary
 $SO(N)$ spinning particle model
Gauge fixing
Gauge fixed partition function
Even N
Odd N
 $Dof(D, N)$
Pashnev and Sorokin model
 $Dof(D, PS)$
Conclusion
Outlook
The end

- Would be interesting to study the one-loop partition function of this model coupled to AdS background
- and study from the worldline point of view how one could introduce more general couplings.
- One could also enlarge the analysis to $osp(2p, Q)$ spinning particle and try to understand if they are related to partially massless HS in AdS

Summary
 $SO(N)$ spinning particle model
Gauge fixing
Gauge fixed partition function
Even N
Odd N
 $Dof(D, N)$
Pashnev and Sorokin model
 $Dof(D, PS)$
Conclusion
Outlook
The end

THANK YOU FOR YOUR ATTENTION

Summary

$SO(N)$ spinning
particle model

Gauge fixing

Gauge fixed partition
function

Even N

Odd N

$Dof(D, N)$

Pashnev and Sorokin
model

$Dof(D, PS)$

Conclusion

Outlook

The end